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Enhancement of Forensic Methods for Digital Images

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Problem definition

- Thesis Objectives
- Digital Forensics and digital image authentication
- Applications of detecting digital forgeries
- > Types of digital image forgeries
- Why Copy-Move Forgery Detection (CMFD) ?
- Families of CMFD algorithms
- Enhanced Filter-based SIFT Approach for CMFD (First algorithm)
- Two Stages Object Recognition Based CMFD Algorithm (Second algorithm)

Outlines

- A Novel Deep Learning Framework for CMFD (Third algorithm)
- Research Outputs
- Conclusion
- Future Work

Problem Definition

Vision does not mean believing



In year 1865: the left is the forged photograph after General Francis P. Blair was added at the rightmost position and shown on right is the original photograph.

Problem Definition

Vision does not mean believing



Forged image used from North Korea to obscure the rumors of Kim Jong-II's death [2]

Problem Definition

Vision does not mean believing





Onset of BBC news about Iranian nuclear experiments

Thesis Objectives

- > Building a general map in the areas of:
 - Digital image forensics
 - Copy-Move forgery
 - > Evaluate existing CMFD algorithms
- > Enhancing the existing algorithms of CMFD
- Building a new CMFD algorithms which outperform the traditional algorithms in efficiency, speed, and computational cost

Digital Forgeries



Digital Image Authentication



Digital Image Authentication

>Active authentication [3-4]:

- Need a previous knowledge of the image
- > Embedded on the original image and checked in the other side
- Take processing Time to embed and check

Passive authentication [3-4]:

> Does not need any previous knowledge of the image

Applications Digital Image Forgeries

- > Military images authentication
- Intelligence images authentication
- > Image authentication for using as evidences in courts
- Detecting of electronic crimes
- > Detecting forgeries in electronic documents
- Counterfeit currency
- Defaming of persons
- Social media

- Copy-move Forgery
- Image splicing or composing
- Image resampling
- Image retouching or Enhancing
- Image Morphing

Images Created by Graphical Software

Copy-move Forgery: use one image only to duplicate or hide one or more object in the same image [5].



The two left images are original while the two right images are forged

• Image splicing or composing: Combining two or more images to create a new image [6].



The left and middle images are original while the right images is composed one

• Image splicing or composing: Combining two or more images to create a new image [6].



The left and middle images are original while the right is the forged image [7]

• **Image splicing or composing:** Combining two or more images to create a new image [6].



New York Times ten most impressive news photos of 2006: A newspaper apologized for the fake picture scandal, in which a photographer manipulated images to show Tibetan antelopes roaming under a bridge on the Qinghai-Tibet Railway 16

• **Image resampling:** Creating a new image with increasing/decreasing in height/width of a specific object in image or in all content of the image [8].





• **Image retouching or Enhancing:** is the process of enhancing an object or image to exhibit or hide a specific feature as coloring, lighting or background changing [9].











• **Image Morphing:** Creating process of gradually changing a shape of an image into another shape in another image and must be applied between two images [9].





• **Images Created by Graphical Software:** is the process of creating a forged image not connected with reality by building its objects and features by computer [10].



Why is Copy-Move Forgery The Most Difficult of Detection?



Copy-Move Forgery Detection Algorithms Methodology



1) Algorithms using DCT: using Discrete Cosine Transform (DCT) to be applied on an image and extract DCT coefficients that are used as features and compare between these coefficients to find the duplicated regions [10].

There are other techniques, which resemble DCT such as Discrete Wavelet Transform (DWT), Principal Component Analysis (PCA), and Singular Value Decomposition (SVD) [11].

- 2) Algorithms using invariant image moments (Shape Analysis):
 - Image moments: a certain particular weighted average of image pixels intensities or functions[12].
 - A. Perform shape analysis.
 - B. Detect image objects after segmentations.
 - C. Offer information about objects orientations.
 - D. Detect central points of each object.
 - E. Report the total image pixels intensities and prosperities.



- **3)** Algorithms Using Texture and Intensity Descriptors:
- > Based on analysis of <u>structure of the image</u> [13] inferred from:
 - Intensity or colors changes: appearing frequently in different patterns.
 - Relationship between pixels: properties in its local area.
 - Edges homogeneity.
 - Spatial arrangement of color: or intensities of a specific region.
 - Spatial relationship between neighbors using statistical method [14].

Tampering harms the texture patterns of an image.

- 4) Algorithms Using Invariant Key Points [15-16]:
 - > It is classified as non-block based algorithms.
 - > Based on extracting image features from all parts of the image.
 - > Invariant against all geometrical transformation attacks such as scaling, rotation, translation, and reflection.

- **5)** Algorithms Using Invariant Key Points:
 - Scale Invariant Feature Transform (SIFT)
 - > A 128 bytes dimensional feature vector is generated for each key-point. The feature vector consists of a row, column, scale, and orientation [17].
 - Speed up Robust Features (SURF) more speed and more stable than SIFT.
 - > A 64 bytes dimensional feature vector is generated for each key-point.

A comparison between copy-move forgery detection

algorithm's families

	Families and Algorithms									
Steps		DCT Maind at al. [19]	Invariant Image Moments	Texture and Intensity Descriptors	Invariant Keypoints	Mutual Information	<u>SVD</u> Zhao atal [24]			
		Maind et al. [19]	Ryu et al. [20]	Sharma et al. [21]	Costanzo et al. [22]	Chakraborty et al. [23]	Zhao et al. 12-41			
Pre-processing	- Grayscale conversions:	-Yes	-Yes	-Yes	-Yes	-No	-Yes -N0			
	- Resizing :	-No	-No	-No	-No	-N0				
Block division	- Division :	-Overlapping circular blocks.	-Overlapping blocks.	-Overlapping blocks.	- Non-overlapping blocks.	- Non-overlapping blocks.	 Overlapping blocks then non-overlapping sub-blocks. Fixed size b x b. 			
	- Block size :	-Fixed size 8x8 pixels.	- fixed size $(B \times B)$.	- fixed size $(B \times B)$.	-fixed size 32 x 32	-fixed size m x n.				
Features Extraction	-Method :	 Apply DCT on each circular block to extract DCT coefficients. 	-Use Zernike moments to extract feature vectors of each block.	- Apply (CSLBP) to each block and Feature of a block representing by a row in the feature matrix.	Extracts SIFT features and use KCR, CHI square distance detector and SVM detector.		 Gets DCT coefficients for each block then, apply SVD on each sub-block to extract the features vector. 			
	-Numbers :	- Four features vector (V1, V2, V3 and V4).	- 12 moments used as feature vectors.	- 2^ (N/2) binary patterns where N is the number of surrounding pixels.	-Depends on SIFT keypoints.		- Depends on sub-blocks numbers.			
	- Sorting :	- Lexicographically representation.	- Lexicographically representation.	- Lexicographically representation.	- Lexicographically representation.		- Lexicographically representation.			
Matching	-Matching Methodology:	- Using Euclidean distance between vectors of two pairs blocks.	-Using locality Sensitive Hashing (LSH) to match similarities between Features vectors among all blocks.	- CSLBP produces 2^(N/2) binary patterns with circular radius R used as features.	- classify the output keypoints to <i>h1,hm</i> and <i>hh</i> then, use CLBA to detects the difference in variance between tested image and CLBA tampered image.	- By histogram, calculate two matrices represents the joint probability distribution of two regions block <i>B(i)</i> & embedded image <i>R(j)</i> with test threshold.	 Using a threshold <i>T</i>(<i>shift</i>) to match similar pairs of blocks with user-specified parameter Td and Euclidian distance threshold (<i>dist</i>). 			
Verification Test		Threshold distance and morphological operation is used.	Use set of SATs thresholds for minimum Euclidean distance in addition to Space Error Reduction procedure (ERP).	Using shift frequency threshold <i>T(shift)</i> and Euclidian distance threshold <i>(dist)</i> .	KCR value should be smaller than its value in the authentic image. If SVM output is higher than a certain threshold value the image is tampered	Using mutual information value, if the regions are not duplicated its mutual information value equal zero otherwise it gives a diagonal value.	The morphologically open operation is applied to fill the holes in marked regions and remove the isolated blocks.			
Computational Complexity		Low computational complexity due to low dimension size of features vectors and block size.	Medium computational complexity because it performs two matching procedure LSH and ERP.	Low computational complexity.	High computational complexity due to large number of its iteration with large number of detectors and features	Low complexity because it not needs to extract features or apply matching procedure.	Low computational complexity due to reducing the size of the checked region by divide the image into two sub-blacks levels.			

A comparison between algorithms robustness against

different processing operations

Families and algorithms		Number of thresholds	Robustness against intermediate processes			Robustness against post-processing operations			Estimate the affine	
			Reflection	Rotation	Scaling	Illumination changes	JPEG compression	Blurring	Gaussian white noise	transform
DCT	Maind et al. [19]	2	No	No	No	No	Yes	Yes	Yes	No
Invariant Image Moments	Ryu et al. [20]	4	Yes	Yes	No	No	Yes	Yes	Yes	Yes
Texture and intensity	Sharma et al. [21]	2	No	No	No	No	Yes	Yes	Yes	No
Invariant Keypoints	Costanzo et al. [22]	3	Yes	Yes	Yes	No	Yes	Yes	Yes	Yes
Mutual Information	Chakrabor ty [23]	1	No	No	No	Yes	No	No	No	No
SVD	Zhao et al. [24]	3	No	No	No	No	Yes	Yes	Yes	No

Enhanced Filter-based SIFT Approach for CMFD (First algorithm)



Forged image



Gray-Scale image



Filtered image



SIFT features extracted



Features matching & forgery detection



Original image

Enhanced Filter-based SIFT Approach for CMFD (First algorithm)

• Extracting SIFT features, mapping and matching



Enhanced Filter-based SIFT Approach for CMFD (First algorithm)

• Experimental Results:

Datasets:

The proposed algorithm is using the most famous four datasets MICC-F220 [25], MICC-F2000 [25], MICC-F600 [26], and SATS-130 [27].

Dataset	Composition	Size of Images	Size of Forged Region
MICC-F220	Consisted of 220 images divided into 110 tampered images and	Between 722×480 and 800×600 pixels	The forged region represents 1.2% of the
	110 originals.	2010 1526 1	whole image.
MICC-F2000	divided into700 tampered images and1300 originals.	2048×1536 pixels	represents 1.12% of the whole image.
MICC-F600	Consisted of 600 images divided into 152 tampered images and 448 originals.	Between 800×532 and 3888×2592 pixels	The forged regions sizes are varied from one image to another.
SATs-130	Consisted of 96 images divided into 48 tampered images and 48 originals.	Between 1024×683 and 3264×2448 pixels	The forged regions sizes are varied from one image to another.
















• Experimental Results:

Datasets:

Ten different combinations of geometric transformations applied to the original patch for the MICC-F220 dataset [25]

Attack	θ °	s_x	s_y]	Attack	θ °	s_x	s_y
A	0	1	1		F	0	1.2	1.2
B	10	1	1		G	0	1.3	1.3
C	20	1	1		H	0	1.4	1.2
D	30	1	1		I	10	1.2	1.2
E	40	1	1			20	1.4	1.2

• Experimental Results:

> Datasets:

Fourteen different combinations of geometric transformations applied to the original patch for the MICC-F2000 dataset [25]

Attack	θ°	s_x	s_y]	Attack
a	0	1	1		h
b	0	0.5	0.5		i
c	0	0.7	0.7		j
d	0	1.2	1.2		1
e	0	1.6	1.6		m
f	0	2	2		n
g	0	1.6	1.2		0

Attack	θ °	s_x	s_y
h	0	1.2	1.6
i	5	1	1
j	30	1	1
1	70	1	1
m	90	1	1
n	40	1.1	1.6
0	30	0.7	0.9

- Experimental Results:
 - > Datasets:

For dataset MICC-F600, 448 original image and 152the forged images

38 images	Forged by copying one patched region, apply transition, and then move.
38 images	Forged by copying two or three patched regions, apply transition, and then move.
38 images	Forged by copying one patched region, rotated by 30 degrees, and then move.
38 images	Forged by copying one patched region, rotated by 30 degrees, scale by 120%, and then move.

• Experimental Results:

Testing Metrics:

$$TPR = \frac{T_P}{(T_P + F_N)} = (1 - FNR)$$

$$FPR = \frac{F_P}{(F_P + T_N)} = (1 - TNR)$$

$$FNR = \frac{F_N}{(F_N + TP)}$$

$$TNR = \frac{T_N}{(T_N + F_P)}$$

True Positive (T_P)
 False Positive (F_P)
 False Negative (F_N)
 True Negative (T_N)

• Experimental Results:

A) Metric parameters values after applying high-pass filter and applying SIFT algorithm & forgery detection

	MICC-F220	MICC-F600	MICC-F2000	SATS-130
TPR %	99.09	89.24	95.1	76.2
FPR %	9.01	7.13	7.2	11.33
TNR %	90.99	92.87	92.8	88.67
FNR %	0.91	10.76	4.9	23.8

B) Metric parameters values after applying **low-pass Gaussian filter** and applying SIFT algorithm & forgery detection with variable values of cutoff frequency

		MICO	C-F220		MICC-F600			
	TPR %	FPR %	TNR %	FNR %	TPR %	FPR %	TNR %	FNR %
fc=160	98.18	19.09	80.91	1.82	80.2	22.03	77.97	19.8
fc=180	97.87	14.55	85.45	2.13	87.5	16.1	83.9	12.5
fc=200	98.18	19.09	80.91	1.82	85.1	18.02	81.98	14.9
fc=220	96.01	13.55	86.45	3.99	82.7	20.13	79.87	17.3
	MICC-F2000							
		MICC	-F2000			SAT	S-130	
	TPR %	MICC FPR %	-F2000 TNR %	FNR %	TPR %	SAT FPR %	S-130 TNR %	FNR %
fc=160	TPR % 89.3	MICC FPR % 17.6	-F2000 TNR % 82.4	FNR % 10.7	TPR % 71.73	SAT FPR % 16.83	S-130 TNR % 83.17	FNR % 28.27
fc=160 fc=180	TPR % 89.3 94.8	MICC FPR % 17.6 12.1	TNR % 82.4 87.9	FNR % 10.7 5.2	TPR % 71.73 79.32	SAT FPR % 16.83 27.51	S-130 TNR % 83.17 8473.	FNR % 28.27 20.68
fc=160 fc=180 fc=200	TPR % 89.3 94.8 91.2	MICC FPR % 17.6 12.1 16.1	TNR % 82.4 87.9 83.9	FNR % 10.7 5.2 8.8	TPR % 71.73 79.32 74.8	SAT FPR % 16.83 27.51 14.2	S-130 TNR % 83.17 8473. 85.8	FNR % 28.27 20.68 25.11

C) Metric parameter values from applying Butterworth low pass filter and applying SIFT algorithm & forgery detection with different values of cutoff frequency

		MICO	C-F220		MICC-F600			
	TPR %	FPR %	TNR %	FNR %	TPR %	FPR %	TNR %	FNR %
fc=160	99.09	13.64	86.36	0.91	79.38	9.35	90.64	20.62
fc=180	100	5.05	94.95	0	85.5	2.7	97.3	14.5
fc=200	99.09	9.09	90.91	0.91	88.75	12.68	87.32	11.25
fc=220	95.45	4.54	95.46	4.55	86.25	16.18	83.82	13.75
	MICC-F2000							
		MICC	-F2000			SAT	S-130	
	TPR %	MICC FPR %	-F2000 TNR %	FNR %	TPR %	SAT FPR %	S-130 TNR %	FNR %
fc=160	TPR % 94.9	MICC FPR % 12.11	-F2000 TNR % 87.89	FNR % 5.1	TPR % 76.2	SAT FPR % 21.31	S-130 TNR % 78.69	FNR % 23.8
fc=160 fc=180	TPR % 94.9 96.71	MICC FPR % 12.11 8.76	-F2000 TNR % 87.89 91.24	FNR % 5.1 3.29	TPR % 76.2 81.25	SAT FPR % 21.31 20.83	S-130 TNR % 78.69 79.17	FNR % 23.8 18.75
fc=160 fc=180 fc=200	TPR % 94.9 96.71 94.95	MICC FPR % 12.11 8.76 11.15	-F2000 TNR % 87.89 91.24 88.85	FNR % 5.1 3.29 8.05	TPR % 76.2 81.25 79.17	SAT FPR % 21.31 20.83 16.67	S-130 TNR % 78.69 79.17 83.33	FNR % 23.8 18.75 20.83

D) Metric parameter values after applying high pass filter first then applying Butterworth low pass filter with different values of cutoff frequencies and complete SIFT algorithm & forgery detection

		MICO	C-F220		MICC-F600			
	TPR %	FPR %	TNR %	FNR %	TPR %	FPR %	TNR %	FNR %
fc=160	94.30	10.73	89.27	5.7	81.13	12.15	87.85	18.87
fc=180	100	4.54	95.46	0.02	87.76	5.63	94.37	12.24
fc=200	97.27	6.36	93.64	2.73	91.49	9.37	90.63	8.52
fc=220	99.09	8.18	91.82	0.91	89.64	10.2	89.8	10.36
	MICC-F2000				SATS-130			
		MICC	-F2000			SAT	S-130	
	TPR %	MICC FPR %	C-F2000 TNR %	FNR %	TPR %	SAT FPR %	S-130 TNR %	FNR %
fc=160	TPR % 95.2	MICC FPR % 11.83	-F2000 TNR % 88.17	FNR % 4.8	TPR % 77.53	SAT FPR % 20.15	S-130 TNR % 79.85	FNR % 22.47
fc=160 fc=180	TPR % 95.2 97.18	MICC FPR % 11.83 7.65	-F2000 TNR % 88.17 92.35	FNR % 4.8 2.82	TPR % 77.53 83.18	SAT FPR % 20.15 16.72	S-130 TNR % 79.85 83.28	FNR % 22.47 16.82
fc=160 fc=180 fc=200	TPR % 95.2 97.18 95.29	MICC FPR % 11.83 7.65 10.89	-F2000 TNR % 88.17 92.35 89.11	FNR % 4.8 2.82 4.71	TPR % 77.53 83.18 80.27	SAT FPR % 20.15 16.72 15.86	S-130 TNR % 79.85 83.28 84.14	FNR % 22.47 16.82 19.73

Enhanced Filter-based SIFT Approach for CMFD

Comparison between the proposal and traditional methods results

	MICC-F220				MICC-F600			
	TPR %	FPR %	TNR %	FNR %	TPR %	FPR %	TNR %	FNR %
The proposal	100	4.54	95.46	0	91.49	9.37	90.63	8.52
Amerini et al. [22]	100	8	92	0	69.2	12.5	87.5	30.8
Amerini et al. [23]	N/A	N/A	N/A	N/A	81.6	7.27	92.73	18.4
Christlein et al. [24]	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
		MICC	-F2000			SAT	S-130	
	TPR %	FPR %	TNR %	FNR %	TPR %	FPR %	TNR %	FNR %
The proposal	97.18	7.65	92.35	2.82	83.18	16.72	83.28	16.82
Amerini et al. [22]	93.42	11.61	88.39	6.58	N/A	N/A	N/A	N/A
Amerini et al. [23]	94.86	9.15	90.85	5.14	N/A	N/A	N/A	N/A
Christlein et al. [24]	N/A	N/A	N/A	N/A	79.17	11.63	88.37	20.83

Comparison between the proposed method and Amerini et al. [25] performance against different values of JPEG compression

JPEG Quality	The p	roposal	Amerini et al. [25]		
Factor	TPR%	FPR%	TPR%	FPR%	
100	97.18	7.65	93.42	11.61	
75	97.15	7.65	93.72	12.07	
50	97.09	7.47	93.16	11.15	
40	97.83	7.30	92.14	11.13	
20	97.31	6.89	87.15	10.46	

Comparison between the proposed method and Amerini et al. [25] performance against values of Gaussian noise SNR (db) applied on whole images

SNR	The p	roposal	Amerini et al. [22]		
(db)	TPR%	FPR%	TPR%	FPR%	
50	97.18	7.65	93.71	11.46	
40	97.15	7.65	94.14	11.69	
30	95.37	7.21	92.00	11.46	
20	93.13	6.78	82.42	8.15	

- Combined Attacks Tests
 - Gaussian noise adding with SNR = 50, and then Gamma correction with value 0.7.
 - Gaussian noise adding with SNR = 50, and then JPEG compression with quality 50.
 - Gamma correction with value 0.7, and then JPEG compression with quality 50.
 - Gaussian noise with SNR = 50, then Gamma correction with value 0.7, and then JPEG compression with quality 50.

Combined Attacks Tests

Geometric transformations that can be applied sequentially on the tampered patched areas before pasting to the original images

Attack No.	θ	s _x	s _y	Attack No.	θ	S _x	s _y
1	0	1	1	7	5	1	1
2	0	0.5	0.5	8	20	1	1
3	0	0.7	0.7	9	30	1	1
4	0	1.2	1.2	10	50	1	1
5	0	1.6	1.6	11	70	1	1
6	0	2	2	12	90	1.5	1.5

Comparison between the proposed method and Amerini et al. [25] performance against different types of combined attacks applied on patched areas only

Combined Attack Type	Algorithm	TPR%	FPR%
Gaussian Noise with	Amerini et al. [25]	85.71	14.29
Gamma correction attack	The Proposal	100	7.14
Gaussian Noise with	Amerini et al. [25]	86.75	14.80
JPEG compression attack	The Proposal	95.06	18.30
Gamma correction with	Amerini et al. [25]	87.5	12.4
JPEG compression attack	The Proposal	93.5	14.1
Gaussian Noise with Gamma correction with	Amerini et al. [25]	87.5	12.4
JPEG compression attack	The Proposal	91.3	14.1

- We developed a two stages CMFD approach:
 - The first stage is responsible for detecting the copy-move forged images and the images that candidate to be original (Matching Stage).
 - The second stage is applied on the candidate categorized to be original image, either to ensure their integrity or to detect a copy-move forgery within this candidate (Refine Matching Stage).



Tested Image



Binary Image



Closed morphological image



Original image



Objects localization image



Edge detected image



Two Stages Object Recognition Based CMFD Algorithm (Second algorithm) • Object Detection:

A) close morphological operation:



- > Removes small holes resulted from projections and connects small cracks in its boundaries.
- > Exhibits object outlines by growing the foreground pixels and detect boundaries or contours of that object.
- > Shrinks the background holes or points belonging to these regions for the distinctness of region's borders.

VS

Object detection:

A) <u>close morphological operation</u>:



Close Morphological operation



Open Morphological operation

- Object detection:
- **B) Edge detection:**
- > Using Sobel operator
 - Noise reduction
 - Edge enhancement
 - Edge localization

Other types that we trying:

1) Canny operator. 2) Roberts operators. 3) Prewitt operator. 4) Laplacian operator.

Two Stages Object Recognition Based CMFD Algorithm (Second algorithm) • Object Detection:

C) Image segmentation:



Scanning the edge detected, pixel by pixel, from top to bottom and left to right to find the connected pixel regions based on blobs.

Each pixel takes a label, being either foreground or background, according to its intensity value.

➢After assigning each pixel to a specific foreground object or a background region, objects bounding boxes are created.
62





Image candidate to be original from matching stage



Binary Image





Edge detected image



Opened morphological image



Edge detected image



Regions resulted





Merged regions from both close and open operations





Original image

Image candidate to be original from matching stage



Binary Image





Edge detected image



Opened morphological image



Edge detected image



Regions resulted





Merged regions from both close and open operations



Original image



• Experimental Results:

> Datasets:

Dataset	Composition	Size of Images	Size of Forged Region	
MICC-F220	Consisted of 220 images divided	Between 722×480 and	The forged region	
	into 110 tampered images and	800×600 pixels	represents 1.2% of the	
	110 originals.		whole image.	
MICC-F2000	Consisted of 2000 images	2048 × 1536 pixels	The forged region	
	divided into700 tampered images		represents 1.12% of the	
	and1300 originals.		whole image.	
MICC-F600	Consisted of 600 images divided	Between 800×532 and	The forged regions sizes	
	into 152 tampered images and	3888 × 2592 pixels	are varied from one	
	448 originals.		image to another.	
SATs-130	Consisted of 96 images divided	Between 1024×683 and	The forged regions sizes	
	into 48 tampered images and 48	3264 × 2448 pixels	are varied from one	
	originals.	6000	image to another.	

Two Stages Object Recognition Based CMFD

Algorithm (Second algorithm)

> Testing Metrics:

$$\begin{split} TPR &= \frac{T_{P}}{(T_{P} + F_{N})} = (1 - FNR) \\ FPR &= \frac{F_{P}}{(F_{P} + T_{N})} = (1 - TNR) \\ FNR &= \frac{F_{N}}{(F_{N} + TP)} \\ TNR &= \frac{T_{N}}{(T_{N} + F_{P})} \\ ACC &= \frac{(T_{N} + T_{P})}{(T_{P} + F_{P} + T_{N} + F_{N})} \times 100 \\ MCC &= \frac{(T_{P} \times T_{N}) - (F_{P} \times F_{N})}{\sqrt{((T_{P} + F_{P}) \times (T_{P} + F_{N}) \times (T_{N} + F_{P}) \times (T_{N} + F_{N}))}} \times 100 \end{split}$$

CT = Computational Time

- Experimental Results:
- Results of applying the proposed matching stage only

Datasets	MICC-F220	MICC-F2000	MICC-F600	SATS-130
Metrics				
TPR	89.09%	87.40%	82.34%	80.47%
FPR	8.18%	12.35%	29.09%	21.28%
FNR	10.91	12.6%	17.66%	19.53%
TNR	91.82%	87.35%	70.91%	78.72%
ACC	90.45%	84.23%	70.79	69.89%
MCC	80.94%	72.34%	58.18%	56.26%
CT (mm:ss)	2:12	30:58	14:30	3:20

- Experimental Results:
- Results of applying the proposed two-stage CMFD algorithm

Datasets	MICC-F220	MICC-F2000	MICC-F600	SATS-130
Metrics				
TPR	100%	98.40%	94.50%	91.67%
FPR	1.80%	6.35%	11.35%	20.83%
FNR	0%	1.60%	5.50%	8.33%
TNR	98.20%	93.65%	88.65%	79.17%
ACC	99.09%	93.55%	91.05%	85.42%
MCC	98.20%	83.39%	80.79%	71.39%
CT(mm:ss)	2:48	46:58	17:37	7:24

- Experimental Results:
- TPR values for matching stage only Vs. TPR values for matching & refining stages.



FPR values for matching stage only Vs. FPR values for matching & refining stages.



- Experimental Results:
- ACC values for matching stage only Vs. ACC values for matching & refining stages.



MCC values for matching stage only Vs. MCC values for matching & refining stages.


- Experimental Results:
- Comparison between proposed algorithm and previously reported methods on MICC-F220.

	The Proposed	Amerini et al.	Amerini et	Mishra et al.	Kaur et al.
	Algorithm	[25]	al. [26]	[28]	[29]
TPR	100 %	100 %	100%	73.64 %	97.27 %
FPR	1.80%	8%	6%	3.64 %	7.27 %
FNR	0%	0%	0%	26.36 %	2.73 %
TNR	98.20%	92%	94%	96.36 %	92.73 %
CT (mm:ss)	2:48	24:13	17:05	0:2.85	N/A

- Experimental Results:
- Comparison between proposed algorithm and previously reported methods on MICC-F2000 dataset.

	The Proposed	Amerini et al.	Amerini et al.
	Algorithm	[25]	[26]
TPR	98.40 %	93.42 %	94.86 %
FPR	6.35 %	11.61 %	9.15 %
FNR	1.60 %	6.58 %	5.14 %
TNR	93.65 %	88.39 %	90.85 %
CT (mm:ss)	46:58	312:18	180:15

- Experimental Results:
- Comparison between proposed algorithm and previously reported methods on MICC-F600 dataset.

	The Proposed	Amerini et al.	Amerini et al.
	Algorithm	[25]	[26]
TPR	94.50 %	69.20 %	81.60 %
FPR	11.35 %	12.50 %	7.27 %
FNR	5.50 %	30.80 %	18.40 %
TNR	88.65 %	87.50 %	92.73 %
CT (mm:ss)	17:37	115:00	76:21

- Experimental Results:
- Comparison between proposed algorithm and previously reported methods on SATS-130 dataset.

	The Proposed	Amerini et al.	Christlein et	Amerini et al.
	Algorithm	[25]	al. [27]	[26]
TPR	91.67 %	67.13 %	79.17 %	79.35 %
FPR	20.83 %	11.89 %	11.63 %	14.51 %
FNR	8.33 %	32.87 %	20.83 %	20.65 %
TNR	79.17 %	88.11 %	88.37 %	85.49 %
CT (mm:ss)	7:24	47:00	N/A	35:31

- Developing a novel deep learning framework for CMFD approach (develop a fast and efficient algorithm by:)
 - 1) Achieve higher performance
 - Increasing detection accuracy.
 - > Decreasing the loss values or the misclassification values of CMFD.
 - 2) Speeding up the forgery detection process by decreasing the computational time and computational cost.
 - Building a high performance classification system using Convolutional Neural Network (CNN).



The CNN structure.



The structure of the novel deep learning framework

Deep CMFD system is presented in three phases: the pre-processing phase, the feature extraction phase, and the classification phase.



The structure of the novel deep learning framework

<u>Pre-processing stage:</u>

The input images are resized to the size that is specified in the input layer (input images is 224 × 224).
85



The structure of the novel deep learning framework

<u>The feature extraction stage:</u>

Consists of six Convolution (CNV) layers and each CNV layer is followed by a max pooling layer.
86



The structure of the novel deep learning framework

<u>Global Average Pooling Layer (GAP):</u>

> Last max pooling layer output are vectorized and inserted into the GAP layer.



The structure of the novel deep learning framework

Dense layer:

> The GAP and Dense layers are used as a fully connected layer

<u>The feature extraction stage:</u>

Consists of six Convolution (CNV) layers that its input parameters are arranged in 4 dimensions as:

[No. of samples, Input image width, Input image height, No. of filters used in each layer]

- CNV layers act as features extractors [each CNV layer applies its specific number of filters and produces its feature maps].
- No. of 2-D filters implemented for each layer are 16, 32, 64, 128, 256, and 512 for the CNV layers 1, 2, 3, 4, 5, and 6, respectively.
- Max pooling layer produces a resized pooled feature maps which act as input to the next CNV layer.

CNV and pooling layers summary

[No. of samples, Input image width, Input image height, No. of filters used in each layer]

Pooling: removing some distortion edges in the input of the next layer.

Layer Type	Output Shape
CNV 1	(N. of samples, 224, 224, 16)
Pooling 1	(N. of samples, 112, 112, 16)
CNV 2	(N. of samples, 110, 110, 32)
Pooling 2	(N. of samples, 55, 55, 32)
CNV 3	(N. of samples, 53, 53, 64)
Pooling 3	(N. of samples, 26, 26, 64)
CNV 4	(N. of samples, 24, 24, 128)
Pooling 4	(N. of samples, 12, 12, 128)
CNV 5	(N. of samples, 10, 10, 256)
Pooling 5	(N. of samples, 5, 5, 256)
CNV 6	(N. of samples, 3, 3, 512)
Pooling 6	(N. of samples, 1, 1, 512)
Global Average Layer	(N. of samples, 512)
Dense	(N. of samples, 2)

Max pooling layer:

Produces a resized pooled feature maps which act as input to the next CNV layer.

 $224\times224\times N.$ of samples



To reduce spatial information to 1) decreasing computational cost. 2) decrease chances of overfitting.

- Detecting correspondences between feature maps and demanded categories.
- Reduces overfitting probability by minimizing the total number of parameters utilized in the layer structure.
- > Compatibility of data with the convolution structure.



Dense layer:

- > Used in the classification decision. The dense layer has a soft-max activation function and a class for each possible category (original or forged).
- > GAP layer and dense layer are used as fully connected layer.

- Experimental Results:
 - Datasets:

Dataset	Composition	Size of Images	Size of Forged Region
MICC-F220	Consisted of 220 images divided	Between 722×480 and	The forged region
	into 110 tampered images and	800×600 pixels	represents 1.2% of the
	110 originals.		whole image.
MICC-F2000	Consisted of 2000 images	2048 × 1536 pixels	The forged region
	divided into700 tampered images		represents 1.12% of the
	and1300 originals.		whole image.
MICC-F600	Consisted of 600 images divided	Between 800×532 and	The forged regions sizes
	into 152 tampered images and	3888 × 2592 pixels	are varied from one
	448 originals.		image to another.
SATs-130	Consisted of 96 images divided	Between 1024×683 and	The forged regions sizes
	into 48 tampered images and 48	3264 × 2448 pixels	are varied from one
	originals.	- Martina	image to another.

- Experimental Results:
 - Datasets:
- ✓ SATs-130 is a small dataset (96 images), thus training the CNN with such small dataset causes overfitting.
- ✓ we merged the four datasets (MICC-F220, MICC-F2000, MICC-F600, and SATs-130) to create an extensive dataset as a datasets combination to test SATs-130 dataset in between.
- ✓ The benefit of integrating various datasets extends beyond simply increasing the dataset size, to generalize the evaluation process of the proposed algorithm.

- Experimental Results:
 - <u>Testing Metrics</u>: In addition to Testing Time (*TT*)

 $TPR = \frac{T_P}{(T_P + F_N)} = (1 - FNR)$ $FPR = \frac{F_P}{(F_P + T_{rr})} = (1 - TNR)$ $FNR = \frac{F_N}{(F_N + Tp)}$ $TNR = \frac{T_N}{(T_N + F_P)}$ $ACC = \frac{(T_N + T_{P)}}{(T_P + F_P + T_N + F_N)} \times 100$ LogLoss = 1 - ACC

- Experimental Results:
 - Evaluation Method:

> Evaluated using the k-fold cross validation technique.

- Randomly dividing the dataset into (k) groups (folds) of approximately equal size. The proposed system is trained by (k-1) groups, and the remaining composes the test set.
- The learning process is repeated (k) times to achieve the diversity between the tested images and accomplish a strong evaluation by testing the datasets completely.

	Testing Folds (K-Folds) K=5									
	Fold 1	Fold 2	Fold 3	Fold 4	Fold 5					
aset	Testing	Training	Training	Training	Training					
Data	Training	Testing	Training	Training	Training					
lete	Training	Training	Testing	Training	Training					
lqmc	Training	Training	Training	Testing	Training					
C	Training	Training	Training	Training	Testing					

- <u>Experimental Results:</u>
 - Results of performing the proposed algorithm on MICC-F220 dataset.

Metrics	Accuracy	Log Loss	TPR %	FPR %	FNR %	TNR %	TT (sec)
No. of Epochs	%	%					
15 Epochs	92.18	7.82	86.67	Zero	13.33	100	16.43
25 Epochs	96.15	3.85	92.86	Zero	7.14	100	17.95
35 Epochs	97.62	2.38	95.45	Zero	4.55	100	15.29
50 Epochs	100	Zero	100	Zero	Zero	100	13.96
75 Epochs	100	Zero	100	Zero	Zero	100	14.63
100 Epochs	100	Zero	100	Zero%	Zero	100	17.76

- <u>Experimental Results:</u>
 - > The results of performing the proposed algorithm on MICC-F2000 dataset.

Metrics	Accuracy	Log Loss	TPR %	FPR %	FNR %	TNR %	TT (sec)
No. of Epochs	%	%					
15 Epochs	92.16	7.84	93.18	9.72	6.82	90.28	108.4
25 Epochs	95.1	4.99	96.88	7.89	3.13	92.11	116.6
35 Epochs	98	2	97.73	1.39	2.27	98.61	<u>119.4</u>
50 Epochs	100	Zero	100	Zero	Zero	100	78.6
75 Epochs	100	Zero	100	Zero	Zero	100	93.8
100 Epochs	99.51	0.49	99.24	Zero	0.76	100	90.1

- <u>Experimental Results:</u>
 - > The results of performing the proposed algorithm on MICC-F600 dataset.

Metrics	Accuracy	Log Loss	TPR %	FPR %	FNR %	TNR %	TT (sec)
No. of Epochs	%	%				Q	
15 Epochs	92.1569	7.8431	90.91	5.56	9.09	94.44	32.41
25 Epochs	94.1176	5.8824	93.75	5.26	6.25	94.73	33.07
35 Epochs	96.0784	3.9216	96.77	5.00	3.23	95.00	32.30
50 Epochs	100	Zero	100	Zero	Zero	100	23.97
75 Epochs	100	Zero	100	Zero	Zero	100	25.75
100 Epochs	100	Zero	100	Zero	Zero	100	25.53

Enhanced Filter-based SIFT Approach for CMFD

• <u>Experimental Results:</u>

> The results of performing the proposed algorithm on datasets combination.

Metrics	Accuracy	Log Loss	TPR %	FPR %	FNR %	TNR %	TT (sec)
No. of Epochs	%	%					
15 Epochs	93.57	6.43	94.20	7.04	5.80	92.96	112.82
25 Epochs	95.00	5.00	95.65	5.63	4.35	94.37	114.98
35 Epochs	97.86	2.14	100	4.11	Zero	95.89	117.73
50 Epochs	98.57	1.43	100	2.78	Zero	97.22	112.47
75 Epochs	100	Zero	100	Zero	Zero	100	110.1
100 Epochs	100	Zero	100	Zero	Zero	100	125.39

- <u>Experimental Results:</u>
 - > The proposed algorithm accuracy & log loss for dataset MICC-F220 at No. of epochs equal to 50.



- <u>Experimental Results:</u>
 - > The proposed algorithm accuracy & log loss for dataset MICC-F2000 at No. of epochs equal to 50.



- <u>Experimental Results:</u>
 - > The proposed algorithm accuracy & log loss for dataset MICC-F600 at No. of epochs equal to 50.



- <u>Experimental Results:</u>
 - > The proposed algorithm accuracy & log loss for datasets combination at No. of epochs equal to 75.



• <u>Experimental Results:</u>

> Number of epochs vs. *TT* for dataset MICC-F220.



• <u>Experimental Results:</u>

> Number of epochs vs. *TT* for dataset MICC-F2000.



• <u>Experimental Results:</u>

> Number of epochs vs. *TT* for dataset MICC-F600.



• <u>Experimental Results:</u>

> Number of epochs vs. *TT* for datasets combination.



- <u>Experimental Results:</u>
 - Comparison between proposed algorithm and previously reported methods on MICC-F220 dataset.

	The Proposed Algorithm	Amerini et al. [22]	Amerini et al. [25]	Mishra et al. [30]	Kaur et al. [31]	Elaskily et al. [32]
TPR %	100	100	100	73.64	97.27	100
FPR %	Zero	8	6	3.64	7.27	1.80
FNR %	Zero	Zero	Zero	26.36	2.73	Zero
TNR %	100	92	94	96.36	92.73	98.20
TT (mm:ss)	0:14	24:13	17:05	0:2.85	N/A	2:48

- <u>Experimental Results:</u>
 - Comparison between proposed algorithm and previously reported methods on MICC-F2000 dataset.

	The Proposed	Amerini et al.	Amerini et al.	Elaskily et al.
	Algorithm	[26]	[25]	[32]
TPR %	100	93.42	94.86	98.40
FPR %	Zero	11.61	9.15	6.35
FNR %	Zero	6.58	5.14	1.60
TNR %	100	88.39	90.85	93.65
TT (mm:ss)	01:19	312:18	180:15	46:58

- <u>Experimental Results:</u>
 - Comparison between proposed algorithm and previously reported methods on MICC-F600 dataset.

	The Proposed Algorithm	Amerini et al. [22]	Amerini et al. [25]	Elaskily et al. [32]
TPR %	100	69.20	81.60	94.50
FPR %	Zero	12.50	7.27	11.35
FNR %	Zero	30.80	18.40	5.5
TNR %	100	87.50	92.73	88.65
TT (mm:ss)	0:24	115:00	76:21	17:37
Research Outputs

- Mohamed A. Elaskily, Heba K. Aslan, Fathi E. Abd El-Samie, Osama A. Elshakankiry, Osama S. Faragallah, Mohamed M. Dessouky, "Comparative Study of Copy-Move Forgery Detection Techniques", Intl Conf on Advanced Control Circuits Systems (ACCS) Systems & Intl Conf on New Paradigms in Electronics & Information Technology (PEIT), Alexandria, Egypt, 2017.
- Mohamed A. Elaskily, Heba K. Aslan, Fathi E. Abd El-Samie, Osama A. Elshakankiry, Osama S. Faragallah, Mohamed M. Dessouky, "Performance Evaluation of Some Algorithms for Copy-Move Forgery Detection", Journal of Electrical Systems and Information Technology, Elsevier, accepted for publication.
- Mohamed A. Elaskily, Heba K. Aslan, Mohamed M. Dessouky, Fathi E. Abd El-Samie, Osama S. Faragallah, Osama A. Elshakankiry, "Enhanced Filter-based SIFT Approach for Copy-Move Forgery Detection", Menoufia Journal of Electronic Engineering Research (MJEER), Vol. 28, No. 1, Jan. 2019.
- Mohamed A. Elaskily, Heba A. Elnemr, Mohamed M. Dessouky, Osama S. Faragallah, "Two Stages Object Recognition Based Copy-Move Forgery Detection Algorithm", Multimedia Tools and Applications, DOI :10.1007/s11042-018-6891-7, 30, Nov. 2018.
- Mohamed A. Elaskily, Heba A. Elnemr, Ahmed Seddik, Mohamed M. Dessouky, Osama Elshakankiry, Heba K. Aslan, Osama S. Faragallah, Fathi E. Abd El-Samie, "A Novel Deep Learning Framework for Copy-Move Forgery Detection", Multimedia Tools and Applications, Vol. 79, No. 6, March 2020.

Research Outputs

Mohamed A. Elaskily, Haider Alkinani, Ahmed Seddik, Mohamed M. Dessouky, "Deep learning based algorithm (ConvLSTM) for Copy Move Forgery Detection", Journal of Intelligent and Fuzzy Systems, Vol. 40, No. 3, PP. 4385-4405, March 2021.

Research Project: "Digital multimedia Forensics Investigations"

Fund: Sapienza University of Rome, Faculty of Computer Science and Artificial Intelligence, Jeddah University, Saudi Arabia kingdom.

Members:

- Prof. Dr. Prof. Irene Amerini, Sapienza University of Rome, Italy.
- Dr. Mohamed A. Elaskily, Electronic Research Institute (ERI), Egypt.
- Dr. Mohamed M. Dessouky, Faculty of Electronic Engineering, Egypt.
- > Dr. Ahmed Sedik, Faculty of Artificial Intelligence, Kafrelsheikh University, Egypt.

Conclusion

- Copy-move forgery is the most difficult type to detect between all digital image forgeries.
- Copy-move forgery detection algorithms which is based on image invariant keypoints are the most efficient algorithms.
- Invariant keypoints based algorithms are characterized by their efficiency against intermediate processes such as rotation, scaling, reflection, translation, and against other post-processing operations such as JPEG compression, blurring, and Gaussian noise.
- Enhanced Filter-based SIFT Approach for CMFD able to give efficient results against different types of attacks which used for hiding copy-move forgeries.



- Enhanced Filter-based SIFT Approach for CMFD using SIFT features to give efficient forgery detection speed and results.
- Enhanced Filter-based SIFT Approach for CMFD show efficiency against rotation, scaling, reflection, translation, and against other post-processing operations such as blurring, Gaussian noise adding, JPEG compression, and Gamma correlation.
- Two Stages Object Recognition Based CMFD Algorithm presents a novel CMFD methodology that is based on segmenting the target image into different objects, and exploring the similarity among these objects.
- This method based on two consecutive stages; matching stage and refinement stage.

Conclusion

- In the matching stage, the candidate image is categorized into forged or original, while the refinement stage aims to certify the originality of the image that is classified as original in the matching stage.
- Two Stages Object Recognition Based CMFD Algorithm shows effectiveness with different datasets under different cloning conditions whether single or multiple cloning.
- Experimental results confirm that the proposed algorithm offers very low computational time comparing with other existing algorithms.
- This low computational time results from using SURF algorithm in addition to build the objects' catalog, which contains all the objects in the tested image, facilitates the matching process.



- demonstrates a novel CMFD methodology based on deep learning approaches.
- Another contribution is the development of a CNN classification system to classify the candidate images for two classes original or tamper.
- The CNN system extracts image features and builds feature maps. Then, the CNN uses the average of the produced feature maps and automatically searches for the features correspondences and dependencies.
- After training the CNN, the system is ready to test and classify the images to detect the copy-move forgery.
- > The experimental results prove that the proposed algorithm offers a very low *TT* comparing with other algorithms.
- > The overall result indicates that the deep learning-based proposed algorithm extensively outperforms the reported algorithms according to its performance and *TT*.

Future Work

- In the future work, CNN modification may be performed to further speed up the proposed algorithm.
- Searching for more challenged datasets may be fulfilled to test the suggested technique. Moreover, deep learning techniques may be applied to detect other types of digital image forgeries.
- Mobile-based and Web-based CMFD algorithm may be developed.
- > Video forensics is a big new challenge will be breaking in.



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Thank you